# Symmetry operators and separation of variables for the Dirac equation 

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## Hamilton-Jacobi, Helmholtz, and Dirac equations

We consider the following equations defined on a $n$-dimensional spin manifold $M$ with contravariant metric tensor $g^{\mu \nu}$ and covariant derivative $\nabla_{\mu}$ :
The Hamilton-Jacobi (HJ) equation for the geodesics:

$$
\begin{equation*}
g^{\mu \nu} \partial_{\mu} W \partial_{\nu} W=m \tag{1}
\end{equation*}
$$

The Klein-Gordon (KG) equation

$$
\begin{equation*}
\mathbb{H} \psi:=g^{\mu \nu} \nabla_{\mu} \nabla_{\nu} \psi-m^{2} \psi=0 \tag{2}
\end{equation*}
$$

The Dirac (D) equation

$$
\begin{equation*}
\mathbb{H} \psi:=i \gamma^{a} \nabla_{a} \psi-m \psi=0 \tag{3}
\end{equation*}
$$

where the $\gamma^{a}$ satisfy

$$
\gamma^{a} \gamma^{b}+\gamma^{b} \gamma^{a}=2 \eta^{a b} \mathbb{I}
$$

and $\eta^{a b}$ denotes the (constant) frame metric.

## Dirac equation

In (3)

$$
\nabla_{a}:=e_{a}^{\mu} \nabla_{\mu}
$$

denotes the frame covariant derivative associated to the spin frame $e_{a}^{\mu}$. The covariant derivative of a spinor $\psi$ is defined by

$$
\nabla_{\mu} \psi=\partial_{\mu} \psi+\frac{1}{8} \Gamma_{\mu}^{a b}\left[\gamma_{a}, \gamma_{b}\right] \psi
$$

where the spin connection is given by

$$
\begin{equation*}
\Gamma_{\mu}^{a b}=e_{\alpha}^{a}\left(\Gamma_{\beta \mu}^{\alpha} e^{b \beta}+\partial_{\mu} e^{b \alpha}\right) \tag{4}
\end{equation*}
$$

$\operatorname{In}(4) \Gamma_{\beta \mu}^{\alpha}$ denotes the the Levi-Civita connection of the metric

$$
g_{\mu \nu}=e_{\mu}^{a} \eta_{a b} e_{\nu}^{b}
$$

induced by the spin frame.

## Separation of Variables: HJ and KG equations

Hamilton-Jacobi equation: sum separability ansatz.
The HJ equation is separable if there exists a separable complete integral of the form

$$
W(\boldsymbol{x}, \boldsymbol{c})=\sum_{i=1}^{n} W_{i}\left(q^{i}, \boldsymbol{c}\right)
$$

where $\boldsymbol{c}=\left(c_{1}, \ldots, c_{n}\right)$ and $\operatorname{det}\left(\frac{\partial^{2} W}{\partial c_{i} \partial q^{\prime}}\right) \neq 0$.
Klein-Gordon equation: product separability ansatz.
The KG equation is separable if there exists a separable solution (satisfying some completeness condition) of the form

$$
\begin{equation*}
\psi(\boldsymbol{x}, \boldsymbol{c})=\prod_{i=1}^{n} \psi_{i}\left(x^{i}, \boldsymbol{c}\right) \tag{5}
\end{equation*}
$$

such the functions $\psi_{i}$ are solutions of a set of ODEs in the variables $x^{i}$.

## Separation of variables: D equation

Dirac equation: local product separability ansatz.
The Dirac equation is said to be separable in a spin frame $e_{a}^{\mu}$ with respect to local coordinates $\boldsymbol{x}:=\left(x^{1}, \ldots, x^{n}\right)$ if there exists a separable solution of the form

$$
\psi(\boldsymbol{x})=\left(\begin{array}{c}
\tilde{\psi}^{1}(\boldsymbol{x})  \tag{6}\\
\vdots \\
\tilde{\psi}^{m}(\boldsymbol{x})
\end{array}\right)
$$

where

$$
\begin{equation*}
\tilde{\psi}^{j}(\boldsymbol{x})=\prod_{i=1}^{n} \psi_{i}^{j}\left(x^{i}\right) \tag{7}
\end{equation*}
$$

where $\psi_{i}^{j}$ for each $j$ are solutions of (systems) of ODEs in variables $x^{i}$.

## Invariant characterization

A valence $p$ symmetric tensor $K_{i_{1}, \ldots, i_{p}}$ that satisfies $\nabla_{\left(\mu_{1}\right.} K_{\left.\mu_{2}, \ldots, \mu_{p+1}\right)}=0$ is called a Killing tensor. For $p=1, K_{\mu}$ is called a Killing vector.
Separability (in general non-orthogonal) of the HJ equation is characterized (Benenti 1997) by the existence of a pair $\left(D_{r}, K\right)$, where $D_{r}$ is an $r$-dimensional Abelian algebra of Killing vectors and $K$ is a $p=2$ Killing tensor which satisfy the following conditions: (i) $K$ is $D_{r}$-invariant with $m=n-r$ pointwwise and pairwise distinct real eigenvalues with orthogonally integrable eigenvectors. (ii) The submanifolds orthogonal to these eigenvectors are $D_{r}$-invariant. ( $r=0$, yields the orthogonal case).
$\mathbb{K}$ is a symmetry operator of $\mathbb{H}$ iff $[\mathbb{K}, \mathbb{H}]=0$.
The first and second order linear symmetry operators are defined by Killing vectors and valence two Killing tensors:
$\mathbb{K}:=K^{\mu} \nabla_{\mu}, \quad \mathbb{K}=\nabla_{\mu} K^{\mu \nu} \nabla_{\nu}$, where in the second case the following additional condition must be satisfied: $\nabla_{\mu}\left(K^{\rho[\mu} R^{\nu]}{ }_{\rho}\right)=0$ where $R^{\nu}{ }_{\rho}$ is the Ricci tensor.
The KG equation is separable iff the corresponding HJ equation is separable and the Robertson condition $K^{\rho[\mu} R^{\nu]}{ }_{\rho}=0$ is satisfied. The separable solutions are eigenvectors of $\mathbb{K}$ with the separation constants as eigenvalues: $\mathbb{K} \psi=\lambda \psi$ (separation paradigm).

## Invariant charcterization: Dirac

We would like to find an analogous characterization for Dirac of the following form:

Geometric conditions on $M$ that imply there exists local coordinates $x^{i}, a$ spin transformation $S$,
which induces the following transformations on spinors and spin frames:

$$
\psi^{\prime}=S \psi \quad e_{a}^{\prime \mu}=J_{\nu}^{\mu} e_{b}^{\nu} \ell_{a}^{b}
$$

where $\ell$ is the image of $S$ in $S O(\eta)$ and $J$ is the Jacobian of the transformation, and a separation matrix $Y$
such that the transformed Dirac equation, which reads

$$
\mathbb{W} \psi^{\prime}=0,
$$

where

$$
\mathbb{W}=Y S \mathbb{H} S^{-1}
$$

is separable in the coordinates $x^{i}$.

## Kerr solution

HJ and KG first separated in the stationary axisymmetric Kerr solution by Carter (1968) in Kerr-Newman coordinates. The separation is non-orthogonal and provides an illustration of Benenti's result. The separation also occurs in the algebraically simpler Boyer-Lindquist (BL) coordinates:
$d s^{2}=\left(1-\frac{2 m r}{\Sigma}\right) d t^{2}+\frac{4 m a r \sin ^{2} \theta}{\Sigma} d t d \phi-\frac{\left(r^{2}+a^{2}\right)^{2} \sin ^{2} \theta}{\Sigma} d \phi^{2}-\frac{\Sigma}{\Delta} d r^{2}-\Sigma d \theta^{2}$,
where $\Sigma=r^{2}+a^{2} \cos (\theta) \quad \Delta=r^{2}-2 m a+a^{2}$. The metric possesses the commuting Killing vectors $\frac{\partial}{\partial t}$ and $\frac{\partial}{\partial \phi}$ (with corresponding momenta $p_{t}$ and $p_{\phi}$ ) and a $p=2$, Killing tensor $K$ defined by the quadratic first integral (see below) which underlies the separation property. One can show that $\left\{p_{t}, p_{\phi}\right\}=\left\{p_{t}, K\right\}=\left\{p_{t}, K\right\}=0$, where $\{$,$\} denotes the$ Poisson bracket.
Carter shows that a solution of the form

$$
S(t, \phi, r, \theta)=-E t+\Phi \phi+S_{\theta}+S_{r},
$$

separates the HJ equation and thus obtains a fourth constant of the motion for the geodesic equations. The solution to Hamilton's equations for the geodesics is thus obtained via Jacobi's theorem.

## Kerr solution contd.

Dirac equation in the Weyl representation separated by Chandrasekhar (1976) WRT BL coordinates in the Kinnersley (null) spin frame.

Chandra procedure analysed by Carter \& McLenaghan (1979) who employ BL coordinates and a symmetric (null) spin frame (Carter 1968).

$$
\begin{gathered}
\boldsymbol{\ell}=(2 \Sigma \Delta)^{-1 / 2}\left(\left(r^{2}+a^{2}\right) \partial_{t}+\Delta \partial_{r}+a \partial_{\phi}\right) \quad \boldsymbol{n}=(2 \Sigma \Delta)^{-1 / 2}\left(\left(r^{2}+a^{2}\right) \partial_{t}-\Delta\right. \\
\boldsymbol{m}=(2 \Sigma)^{-1}\left(-a \sin (\theta) \partial_{t}+i \partial_{\theta}-\csc (\theta) \partial_{\phi}\right),
\end{gathered}
$$

They discovered the underlying commuting symmetry operators which characterize the separation and have the Chandra separation constants as eigenvalues:

$$
\mathbb{K}=i\left(k^{\mu}-(1 / 4) \gamma^{\mu} \gamma^{\nu} \nabla_{\nu} k_{\mu}\right) \quad \mathbb{L}=i \gamma_{5} \gamma^{\mu}\left(f_{\mu}{ }^{\nu} \nabla_{\nu}-(1 / 6) \gamma^{\nu} \gamma^{\rho} \nabla_{\rho} f_{\mu \nu}\right)
$$

where $\nabla_{(\mu} k_{\nu)}=0$ and $f_{(\nu \rho)}=\nabla_{(\mu} f_{\nu) \rho}=0$ (Killing-Yano equation).
The analysis also yields generalized formulae for the separated radial and angular parts (Carter \& McLenaghan 1982) that include not only the full massive, charged Dirac equation but also the massive charged KG equation and the formulae for the neutral, zero mass spin $s=1 / 2,1,2$ wave equations obtained by earlier workers .

## Type D vacuum solution

- Most general first-order commuting symmetry operator (McLenaghan \& Spindel 1979) is a sum of the two operators given previously and

$$
\mathbb{M}=y^{\mu \nu \rho} \gamma_{\nu \rho} \nabla_{\mu}-(3 / 4) \nabla_{\mu} y^{\mu} \gamma_{5}
$$

where $y_{\mu \nu \rho}=y_{[\mu \nu \rho]}$ and $\nabla_{(\mu} y_{\nu) \rho \sigma}=0$.

- Algebra of first symmetry operators investigated by McLenaghan \& Spindel 1979.
- Chandra procedure extended to the class of Petrov type D vacuum solutions and its characterization by first order symmetry operators (Kamran \& McLenaghan 1984).
- Most general first order R-commuting symmetry operators for the massless Dirac equation constructed (Kamran \& McLenaghan 1984).


## Factorizable systems

First general theory of Dirac separability is that of factorizable systems proposed by Miller (1988) as part of his general theory of mechanisms for variable separation in PDEs.
Miller studies systems of the form

$$
\mathbb{D} \psi:=H^{i} \partial_{i} \psi+V \psi=\lambda^{1} \psi
$$

A factorizable system for the above is set of $n$ equations

$$
\partial_{i} \psi=\left(C_{i j} \lambda^{j}-C_{i}\right) \psi
$$

A factorizable system is separable if $\partial_{k} C_{i j}=\partial_{k} C_{i}=0$ for $k \neq i$.
The integrability conditions for a factorizable are satisfied iff there exist a a system of $n-1$ first order differential operators that commute amongst themselves and with $\mathbb{D}$ and have the solutions of the $f s$ as eigenspinors.

## Non-factorizable systems

Fels \& Kamran (1990) show

- that factorizable systems contain all the the separable systems for the Dirac equation on Petrov type D vacuum spacetimes.
- that for $n=4$ there exist non-factorizable systems by giving an example of a metric with a 1-parameter isometry group and for which the Dirac equation admits a non-factorizable separable system characterized by second order symmetry operators. They also provide an example for $n=2$.

It thus seems that a complete theory requires the study of second order symmetry operators.

The first steps in this direction were taken by McLenaghan, Smith \& Walker (2000) and Smith (2002) who in the case $n=4$ computed the general second-order symmetry operator using a two-component spinor formalism.

The remaining slides describe joint work with Carignano, Fatibene, Rastelli \& Smith (2008-2015) for the case $n=2$.

## Separability in 2-dimensions: KG and H equations

If $M$ admits a non-trivial valence two Killing tensor $\boldsymbol{K}$, there exists a coordinate system ( $u, v$ ) such that

$$
\begin{align*}
d s^{2} & =(A(u)+B(v))\left(\mathrm{d} u^{2}+\mathrm{d} v^{2}\right) \quad \text { (Liouville metric) }  \tag{8}\\
\boldsymbol{K} & =(A(u)+B(v))^{-1}\left(B(v) \partial_{u} \otimes \partial_{u}-A(v) \partial_{v} \otimes \partial_{v}\right)
\end{align*}
$$

where $A$ and $B$ are arbitrary smooth functions. The KG equation reads

$$
\mathbb{H} \psi=(A+B)^{-1}\left(\partial_{u u}^{2} \psi+\partial_{v v}^{2} \psi\right)-E \psi=0
$$

Since $R_{\mu \nu}=1 / 2 R g_{\mu \nu}, \mathbb{H}$ admits a second order symmetry operator $\mathbb{K}$ :

$$
\mathbb{K} \psi=(A+B)^{-1}\left(B \partial_{u u}^{2} \psi-A \partial_{v v}^{2} \psi\right)
$$

With the product ansatz $\psi(u, v)=a(u) b(v)$, the KG equation, after multiplication by the separation factor $A+B$, reads $b a^{\prime \prime}+a b^{\prime \prime}-m(A+B) a b=0$, which separates yielding $a^{\prime \prime} / a-m A=-b^{\prime \prime} / b+m B=\lambda$, where $\lambda$ is a separation constant. It follows that separable solution satisfies

$$
\mathbb{K}(a b)=\lambda a b
$$

## Dirac equation separability in 2-dimensions

A choice of gamma matrices valid for both signatures is

$$
\gamma^{1}=\left(\begin{array}{cc}
1 & 0  \tag{9}\\
0 & -1
\end{array}\right), \quad \gamma^{2}=\left(\begin{array}{cc}
0 & -k \\
k & 0
\end{array}\right)
$$

where $k=\sqrt{-\eta}, \eta=\operatorname{det}\left(\eta_{a b}\right)$, and $\eta_{a b}=\operatorname{diag}(1, \pm 1)$ is the frame metric.

The Dirac equation may be written as

$$
\begin{equation*}
\mathbb{D} \psi:=\tilde{A} \partial_{1} \psi+\tilde{B} \partial_{2} \psi+\tilde{C} \psi-\lambda \psi=0 \tag{10}
\end{equation*}
$$

where

$$
\tilde{A}=\left(\begin{array}{cc}
A_{1} & A_{2} \\
-A_{2} & -A_{1}
\end{array}\right) \quad \tilde{B}=\left(\begin{array}{cc}
B_{1} & B_{2} \\
-B_{2} & -B_{1}
\end{array}\right) \quad \tilde{C}=\left(\begin{array}{cc}
C_{1} & -C_{2} \\
C_{2} & -C_{1}
\end{array}\right)
$$

with

$$
\begin{array}{r}
A_{1}=i e_{1}^{1} \quad A_{2}=-i k e_{2}^{1} \quad B_{1}=i e_{1}^{2} \quad B_{2}=-i k e_{2}^{2} \\
C_{1}=-(i / 2) k e_{2}^{\mu} \Gamma_{\mu}^{12} \quad C_{2}=-(i / 2) e_{1}^{\mu} \Gamma_{\mu}^{12} \tag{11}
\end{array}
$$

## Separation

With product separability assumption $\psi_{i}=a_{i}(x) b_{i}(y)$ the D equation reads

$$
\begin{aligned}
& A_{1} \dot{a}_{1} b_{1}+A_{2} \dot{a}_{2} b_{2}+B_{1} a_{1} \dot{b}_{1}+B_{2} a_{2} \dot{b}_{2}+C_{1} a_{1} b_{1}-C_{2} a_{2} b_{2}-\lambda a_{1} b_{1}=0 \\
& A_{2} \dot{a}_{1} b_{1}+A_{1} \dot{a}_{2} b_{2}+B_{2} a_{1} \dot{b}_{1}+B_{1} a_{2} \dot{b}_{2}-C_{2} a_{1} b_{1}+C_{1} a_{2} b_{2}+\lambda a_{2} b_{2}=0
\end{aligned}
$$

## Definition

The Dirac equation is separable in the coordinates $(x, y)$ if there exist a separation matix $\operatorname{diag}\left(R_{1}(x, y), R_{2}(x, y)\right)$ such the equations can be written as

$$
R_{1} a_{i} b_{j}\left(E_{1}^{\times}+E_{1}^{y}\right)=0 \quad R_{2} a_{k} b_{\ell}\left(E_{2}^{×}+E_{2}^{y}\right)=0
$$

for a suitable choice of indices $i, j, k, \ell$, where $E_{i}^{\times}\left(x, a_{j}, \dot{a}_{j}\right)$ and $E_{i}^{y}\left(y, b_{j}, \dot{b}_{j}\right)$. Moreover, the equations

$$
E_{i}^{x}\left(x, a_{j}, \dot{a}_{j}\right)=\mu_{i}=-E_{i}^{y}\left(y, b_{j}, \dot{b}_{j}\right)
$$

define the separation constants $\mu_{i}$.

## Symmetry operators

We construct eigenvalue-type operators $\mathbb{L} \psi=\mu \psi$ with eigenvalues $\mu\left(\mu_{i}\right)$ making use only of the terms $E_{i}^{X}$ and $E_{i}^{y}$. These operators are required to satisfy the following conditions:

- The operators $\mathbb{L}$ are independent of $\lambda$.
- $[\mathbb{L}, \mathbb{D}] \psi=0$ for all $\psi$.
- $\lambda \neq 0$.

TYPES OF SEPARATION
I. $a_{2} \neq a_{2}$ and $b_{1} \neq b_{2}$
II. $a_{1}=a_{2}=a$ and $b_{1} \neq b_{2}$ (or vive-versa)
III. $a_{1}=a_{2}=a$ and $b_{1}=c b_{2}=b(c$ constant $)$

## Results

## Proposition

The only type I separation is associated with the nonsingular Dirac operator and associated symmetry operator of the forms

$$
\mathbb{D}:=\left(\begin{array}{cc}
0 & 1 \\
-1 & 0
\end{array}\right) \partial_{x}+\left(i / R_{1}(y)\right)\left(\begin{array}{cc}
1 & 0 \\
0 & -1
\end{array}\right) \partial_{y} \quad \mathbb{L}=\left(\begin{array}{cc}
\partial_{x}^{2} & 0 \\
0 & \partial_{x}^{2}
\end{array}\right)
$$

The separable spin frame is given by

$$
e_{1}^{1}=e_{2}^{2}=0 \quad e_{1}^{2}=1 \quad e_{2}^{1}=R_{1}(y)
$$

The corresponding coordinates separate the geodesic Hamilton-Jacobi equation. If the Riemannian manifold is the Euclidean plane, the coordinates, up to a rescaling, coincide with polar or Cartesian coordinates.

Separability is also possible for equations of Type II which give rise to first order operators. Separability is not possible for Type III.

## Conclusions from the analysis

- Dirac separability implies Hamilton-Jacobi Helmholtz separability.
- Dirac separability implies $M$ admits a 1-parameter isometry group.


## Second order symmetry operators

A second order symmetry operator for the Dirac equation is an operator of the form

$$
\mathbb{K}=\mathbb{E}^{a b} \nabla_{a b}+\mathbb{F}^{a} \nabla_{a}+\mathbb{G} \mathbb{I},
$$

which satisfies the defining relation

$$
\begin{equation*}
[\mathbb{K}, \mathbb{D}]=0 \tag{13}
\end{equation*}
$$

The coefficients $\mathbb{E}^{a b}, \mathbb{F}^{a}, \mathbb{G}$ are matrix zero-order operators and $\nabla_{a b}=\frac{1}{2}\left(\nabla_{a} \nabla_{b}+\nabla_{b} \nabla_{a}\right)$. The condition (13) is equivalent to

$$
\left\{\begin{array}{l}
\mathbb{E}^{(a b} \gamma^{c)}-\gamma^{\left(c \mathbb{E}^{a b)}\right.}=0 \\
\mathbb{F}^{(a} \gamma^{b)}-\gamma^{(b} \mathbb{F}^{a)}=\gamma^{c} \nabla_{c} \mathbb{E}^{a b} \\
\mathbb{G} \gamma^{a}-\gamma^{a} \mathbb{G}=\gamma^{c} \nabla_{c} \mathbb{F}^{a}-\frac{R}{4}\left(\mathbb{E}^{a b} \gamma^{c}+\gamma^{c} \mathbb{E}^{a b}\right) \epsilon_{b c} \gamma+\frac{R}{6}\left(\mathbb{E}^{b d} \gamma^{c}+2 \gamma^{c} \mathbb{E}^{b d}\right) \epsilon^{a}{ }_{d} \epsilon_{l} \\
\gamma^{a} \nabla_{a} \mathbb{G}=\frac{R}{8}\left(\mathbb{F}^{a} \gamma^{b}+\gamma^{b} \mathbb{F}^{a}\right) \gamma \epsilon_{a b}+\frac{1}{12}\left(2 \mathbb{E}^{a b} \gamma^{c}+\gamma^{c} \mathbb{E}^{a b}\right) \gamma \epsilon_{a c} \nabla_{b} R \tag{14}
\end{array}\right.
$$

where $R$ denotes the Ricci scalar of $g_{\mu \nu}$.

## Solution of defining equations

Expand $\mathbb{E}^{a b}$ in the basis $\left(\mathbb{I}, \gamma_{1}, \gamma_{2}, \gamma\right)$ of the Clifford algebra $\mathbb{C}(2)$ :

$$
\mathbb{E}^{a b}=e^{a b} \mathbb{I}+e_{c}^{a b} \gamma^{c}+\hat{e}^{a b} \gamma,
$$

where the coefficients $e^{a b}, e_{c}^{a b}, \hat{e}^{a b}$ are point functions in $M$. The solution of the first equation of (14) is given by

$$
\mathbb{E}^{a b}=e^{a b} \mathbb{I}+2 \alpha^{(a} \gamma^{b)},
$$

where the $e^{a b}$ and the $\alpha^{a}$ are the frame components of arbitary valence two tensor and vector fields.
Setting

$$
\mathbb{F}^{a}=f^{a} \mathbb{I}+f_{b}^{a} \gamma^{b}+\hat{f}^{a} \gamma
$$

we find that the most general solution of the first and second equations of (14) may be written as

$$
\left\{\begin{array}{l}
\mathbb{E}^{a b}=K^{a b} \mathbb{I}+2 \alpha^{(a} \gamma^{b)} \\
\mathbb{F}^{a}=f^{a} \mathbb{I}+\left(\gamma^{c} \nabla_{c} \alpha^{a}+A \gamma^{a}\right)+\frac{1}{3} \epsilon_{b c} \nabla^{b} K^{a c} \gamma
\end{array}\right.
$$

## Solution of defining equations

where

$$
\left\{\begin{array}{l}
\nabla^{(a} K^{b c)}=0 \\
\nabla^{(a} \alpha^{b)}=0
\end{array}\right.
$$

Observe that $K^{a b}$ and is necessarily a valence two Killing tensor and $\alpha^{a}$ a Killing vector. Writing

$$
\mathbb{G}=g \mathbb{I}+g_{a} \gamma^{a}+\hat{g} \gamma
$$

we find that the most general solution of the first three equations of (14) is given by

$$
\left\{\begin{array}{l}
\mathbb{E}^{a b}=K^{a b} \mathbb{I}+2 \alpha^{(a} \gamma^{b)} \\
\mathbb{F}^{a}=\left(\zeta^{a}+\nabla_{c} K^{a c}\right) \mathbb{I}+\left(\gamma^{c} \nabla_{c} \alpha^{a}+A \gamma^{a}\right)+\frac{1}{3} \epsilon_{b c} \nabla^{b} K^{a c} \gamma \\
\mathbb{G}=g \mathbb{I}-\frac{R}{4} \alpha_{b} \gamma^{b}+\frac{1}{4} \epsilon_{b a} \nabla^{b} \zeta^{a} \gamma
\end{array}\right.
$$

where

$$
\left\{\begin{array}{l}
A \in \mathbb{C} \\
\nabla^{(d} K^{a b)}=0 \\
\nabla^{(a} \alpha^{b)}=0, \nabla^{(d} \zeta^{b)}=0
\end{array}\right.
$$

## Solution of defining equations

Finally the fourth equation of (14) yields

$$
\begin{equation*}
\nabla_{a} g=-\frac{1}{4} \nabla_{b}\left(R K_{a}^{\cdot b}\right) \quad \Rightarrow \partial_{\mu} g=-\frac{1}{4} \nabla^{\nu}\left(R K_{\mu \nu}\right) \tag{15}
\end{equation*}
$$

This equation locally detemines $g$ and hence the most general second order symmetry operator of the Dirac equation if and only if the right hand side is a closed 1 -form. If the space is flat, $R=0$ and the solution of is $g=$ constant. The integrability condition for (15) is

$$
\begin{equation*}
\nabla_{[\mu} \nabla^{\rho}\left(R K_{\nu] \rho}\right)=0 \tag{16}
\end{equation*}
$$

## CONCLUSION:

The most general second order symmetry operator is defined by a Killing tensor $K_{\mu \nu}$, two Killing vectors $\alpha_{\mu}, \zeta_{\mu}$, a scalar function $g$, and a constant $A$, provided these objects exist on $M$.

## Integrability condition solution

For the Liouville metric (8) The integrability condition (16) reads

$$
\begin{equation*}
(A+B)^{2}\left(A^{\prime} B^{\prime \prime \prime}+A^{\prime \prime \prime} B^{\prime}\right)+6 A^{\prime} B^{\prime}\left(\left(A^{\prime}\right)^{2}+\left(B^{\prime}\right)^{2}\right)-6 A^{\prime} B^{\prime}(A+B)\left(A^{\prime \prime}+B^{\prime \prime}\right)=0 \tag{17}
\end{equation*}
$$

If one of $A$ or $B$ is constant, (17) is trivially satisfied in which case the space admits a Killing vector. In the case $A^{\prime} B^{\prime} \neq 0$, the integrability condition (17) implies that

$$
\left\{\begin{array}{l}
\left(A^{\prime}\right)^{2}=k A^{4}+a_{3} A^{3}+a_{2} A^{2}+a_{1} A+a_{0} \\
\left(B^{\prime}\right)^{2}=-k B^{4}+a_{3} B^{3}-a_{2} B^{2}+a_{1} B-a_{0}
\end{array}\right.
$$

where $a_{i}, i=0,1,2,3$, and $k$ are arbirary constants. If $A$ and $-B$ are taken as coordinates, the metric may be written as

$$
\begin{equation*}
d s^{2}=(A-B)\left(\frac{d A^{2}}{p_{4}(A)}-\frac{d B^{2}}{p_{4}(B)}\right), \tag{18}
\end{equation*}
$$

where $p_{4}(A):=k A^{4}+a_{3} A^{3}+a_{2} A^{2}+a_{1} A+a_{0}$.
The Ricci scalar is given by $R=(A+B) k+\frac{1}{2} a_{3}$. If $k=0$, (18) is the metric of a space of constant curvature.

## First order operators and reducibility

A first order operator is said to be trivial if it has the form $\alpha \mathbb{D}+\beta \mathbb{I}$. Thus the most general first order operator has the form

$$
\left\{\begin{array} { l } 
{ \mathbb { E } ^ { a b } = 0 } \\
{ \mathbb { F } ^ { a } = \zeta ^ { a } \mathbb { I } + A \gamma ^ { a } } \\
{ \mathbb { G } = g \mathbb { I } + \frac { 1 } { 4 } \epsilon _ { b a } \nabla ^ { b } \zeta ^ { a } \gamma }
\end{array} \quad \text { where } \left\{\begin{array}{l}
A, g \in \mathbb{C} \\
\nabla^{(d} \zeta^{b)}=0
\end{array}\right.\right.
$$

There is a one-to-one correspondence between non-trivial first order operators and Killing vectors $\zeta$ on $M$. A second order operator is said to be trivial if it has the form $\mathbb{D} \circ \mathbb{K}_{1}+\mathbb{K}_{1}^{\prime}$, where $\mathbb{K}_{1}$ and $\mathbb{K}_{1}^{\prime}$ denote any first order operators.
Thus the most general non-trivial second order operator has the form

$$
\left\{\begin{array}{l}
\mathbb{E}^{a b}=K^{a b} \mathbb{I} \\
\mathbb{F}^{a}=\nabla_{c} K^{a c} \mathbb{I}+\frac{1}{3} \epsilon_{b c} \nabla^{b} K^{a c} \gamma \\
\mathbb{G}=g \mathbb{I}
\end{array}\right.
$$

$$
\text { where }\left\{\begin{array}{l}
\nabla^{(d} K^{a b)}=0 \\
K^{a b} \neq \lambda \eta^{a b} \\
\nabla_{[\mu}\left(\nabla^{\lambda}\left(R K_{\nu] \lambda}\right)\right)=0
\end{array}\right.
$$

and where $g$ a solution of equation (16). There is a one-to-one correspondence between non-trivial second order operators and Killing tensors $K^{a b}$ on $M$ such that $K^{a b} \neq \lambda \eta^{a b}$ and $\nabla_{[\mu}\left(\nabla^{\lambda}\left(R K_{\nu] \lambda}\right)\right)=0$.

## Separation of variables

It is known that the Dirac equation separates only in coordinate systems separating the Helmholtz equation for the corresponding metric tensor, and only if one at least of these coordinates is associated to a Killing vector.
This is the case for the coordinate system $(u, v)$ for which the metric is in Liouville form, and $u$ is an ignorable coordinate. The appropriate spin-frame in this case is given by

$$
\left(e_{a}^{\mu}\right)=\left(\begin{array}{cc}
0 & \frac{1}{\sqrt{A(u)+B(v)}} \\
-\frac{1}{\sqrt{A(u)+B(v)}} & 0
\end{array}\right),
$$

where $A=0$ and $B(v)=\beta(v)^{-2}$. Assuming that vectors $\alpha$ and $\zeta$ are zero the Dirac operator $\mathbb{D}$ and second order symmetry operator $\mathbb{K}$ may be written in matrix form as

$$
\mathbb{D}=\beta\left[\left(\begin{array}{cc}
0 & -1 \\
1 & 0
\end{array}\right) \partial_{u}+\left(\begin{array}{cc}
i & 0 \\
0 & -i
\end{array}\right) \partial_{V}\right]-\frac{1}{2}\left(\begin{array}{cc}
i & 0 \\
0 & -i
\end{array}\right) \beta^{\prime},
$$

and

$$
\mathbb{K}=\left(\begin{array}{ll}
1 & 0 \\
0 & 1
\end{array}\right) \partial_{u u}^{2}
$$

## Separation of variables

The expressions for $\mathbb{D}$ and $\mathbb{K}$ coincide with the separation scheme earlier. It is an instance of non-factorizable separation of Fels \& Kamran. By computing

$$
\mathbb{D} \psi-m \psi=0
$$

and

$$
\begin{equation*}
\mathbb{K} \psi-\mu \psi=0 \tag{19}
\end{equation*}
$$

with the separation ansatz

$$
\psi=\binom{a_{1}(u) b_{1}(v)}{a_{2}(u) b_{2}(v)}
$$

we obtain the separated equations

$$
\left\{\begin{array}{l}
-\frac{a_{2}^{\prime}}{a_{1}}=-i \frac{b_{1}^{\prime}}{b_{2}}+\frac{i \beta^{\prime}}{2 \beta} \frac{b_{1}}{b_{2}}+\frac{m}{\beta} \frac{b_{1}}{b_{2}} \\
\frac{a_{1}^{\prime}}{a_{2}}=i \frac{b_{2}^{\prime}}{b_{1}}-\frac{i \beta^{\prime}}{2 \beta} \frac{b_{2}}{b_{1}}+\frac{m}{\beta} \frac{b_{2}}{b_{1}}
\end{array}\right.
$$

and, from (19) we have

$$
\left\{\begin{array}{l}
a_{1}^{\prime \prime}=-\mu a_{1}  \tag{20}\\
a_{2}^{\prime \prime}=-\mu a_{2}
\end{array}\right.
$$

## Separation of variables

By introducing separation constants $\mu_{1}$ and $\mu_{2}$ such that $\mu_{1} \mu_{2}=\mu$, the first system gives for the $a_{i}$

$$
\left\{\begin{array}{l}
a_{2}^{\prime}=-\mu_{1} a_{1}  \tag{21}\\
a_{1}^{\prime}=\mu_{2} a_{2}
\end{array}\right.
$$

and for the $b_{i}$

$$
\left\{\begin{array}{l}
-i b_{1}^{\prime}+i \frac{\beta^{\prime}}{2 \beta} b_{1}+\frac{m}{\beta} b_{1}=\mu_{1} b_{2}  \tag{22}\\
i b_{2}^{\prime}-i \frac{\beta^{\prime}}{2 \beta} b_{2}+\frac{m}{\beta} b_{2}=\mu_{2} b_{1}
\end{array}\right.
$$

It is evident that $\mathbb{K}$ provides, via (20), a decoupling relation for the equations (21). On the other hand, (20) can be obtained by applying twice equations (21). The symmetry operators associated with separation are generated by this means in MR. The solutions for the $a_{i}$ are

$$
\left\{\begin{array}{l}
a_{1}=c_{1} \sin (\sqrt{\mu} u)+c_{2} \cos (\sqrt{\mu} u) \\
a_{2}=\sqrt{\frac{\mu_{1}}{\mu_{2}}}\left[-c_{2} \sin (\sqrt{\mu} u)+c_{1} \cos (\sqrt{\mu} u)\right]
\end{array}\right.
$$

where $c_{1}, c_{2} \in \mathbb{C}$.

## Separation of variables

The general solution of (22) can be easily computed in Cartesian coordinates, $\beta(v)=1$ :

$$
\left\{\begin{array}{l}
b_{1}=d_{1} \sin (M v)+d_{2} \cos (M v) \\
b_{2}=\frac{1}{\mu_{1}}\left[\left(d_{1}+i M d_{2}\right) \sin (M v)+\left(d_{2}-i M d_{1}\right) \cos (M v)\right]
\end{array}\right.
$$

where $d_{1}, d_{2} \in \mathbb{C}$ and $M=\sqrt{m^{2}-\mu}$. It is remarkable that, even if the $a_{i}$ and the $b_{i}$ depend on the $\mu_{j}$, the products $\psi_{i}=a_{i} b_{i}$ depend on $\mu$ only.

By setting $\beta$ equal to $1, e^{v}, \sinh (v), \cosh (v), k-\cos (v)$, with $k>1$, respectively, the corresponding Riemannian manifolds are:

- the Euclidean plane in Cartesian and polar coordinates
- the sphere
- the pseudo-sphere
- the torus

For polar coordinates in the Euclidean plane and in the cases of sphere and pseudosphere, equations (22) can be integrated, to obtain solutions respectively in terms of Bessel functions and, on the sphere and pseudosphere, in terms of hypergeometric functions.

## Future directions

- Give a complete invariant characterization for Dirac equation separability comparable to that for the Hamilton-Jacobi and Helmholtz equations.
- Given that the invariant conditions for separability are satisfied, determine a procedure for the transformation to separable form.
- Extend the theory to higher dimensions.


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